## Math 4803 LAST TIME

### April 22, 2024

· <u>Uniqueness</u> for geometrization of Knot Complements.

· Geometrization for surfaces . ] Uniformization

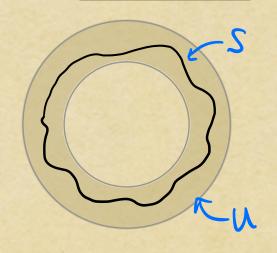
#### TODAY (LAST TIME)

· Geometrization for 3-manifolds of finite topological type.

## Essential surfaces in 3-manifolds

Let (X,d) be a 3-manifold. Our decomposition of (X,d) will involve cutting along essential surfaces—
roughly, surfaces where cutting isn't boring.

A two-sided surface in X is a subset SCX s.t.



3 · a 2-manifold Y;

· a subset UCX;

· a homeomorphism

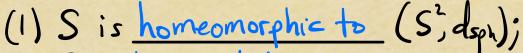
 $\psi: \Upsilon \times (-\epsilon, \epsilon) \longrightarrow U,$ for some  $\epsilon > 0$ , such that  $\psi(\Upsilon \times \{0\}) = S$ 

But (X,d) Contains lots of boring two-sided surfaces: Consider boundaries of small balls.

#### Essential surfaces in 3-manifolds

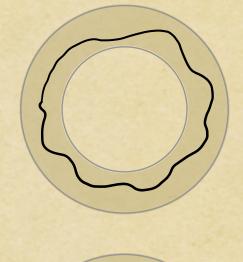
To cut along a surface, we want it to be two-sided, but not boring.

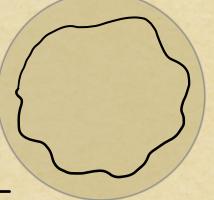
Let (X,d) be a metric space which is a 3-manifold. A subset SCX is an essential sphere if:



(2) S is two-sided

(3) S is not <u>contained in a subset</u>
BCX homeomorphic to (R³, deuc).





A subset PCX is an essential projective plane if

(1) P is homeomorphic to (RP2, dsph);

(2) P is two-sided.

#### Essential surfaces in 3-manifolds

Defining "not boring" for tori is a bit more involved, because tori can bound regions not contained in balls.

A subset TCX is called an essential torus if:

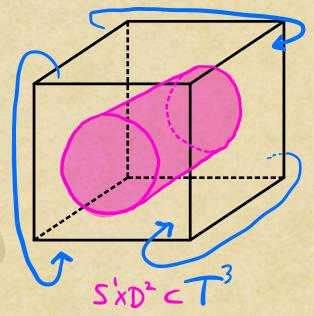


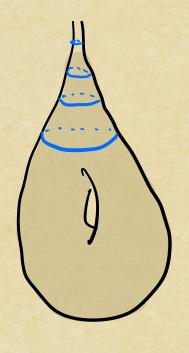
(2) T is two-sided;

(3) Tis not <u>contained</u> in a subset BCX (?) which is homeomorphic to (Ridere);

(4) T does not bound a solid torus in X;

(5) T does not bound a subset of X homeomorphic to Tx [0, 00).

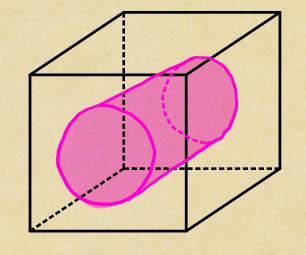




#### Essential surfaces in 3-manifolds Let's be precise about bounding requirements. We'll say that TCX

bounds a solid torus VCX if

there's a homeomorphism



Ψ: (s'xo², Teuc) → (V,d|v) s.t. Ψ(s'xs')=T.



A more complicated sort of solid is the twisted solid torus  $S'\tilde{x}D'$ , obtained as the quotient  $([0,1]xD')/\sim$ , where  $(1,P)\sim(0,P)$ , for every  $P\in D'$ .

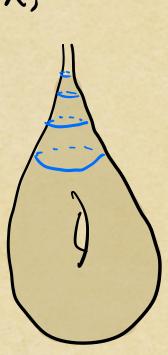
We say that KCX bounds a twisted solid torus VCX if there's a homeomorphism

Ψ: (S'xD2, deve) → (V, dlv) s.t. Ψ(s'xs') = k.

# Essential surfaces in 3-manifolds A subset KCX is called an essential Klein bottle if:

- (1) K is homeomorphic to (K, denc);
  (2) K is two-sided;
- (3) K does not bound a twisted solid torus in X;

(4) K is not the boundary of an infinite collar i.e., & a subset WCX with a homeomorphism P: K2×[0,00) → W such that  $K = \Psi(K^2 \times \{0\})$  and s.t.  $\lim_{t\to\infty}\inf\{d(P_0,P)\mid P\in\Psi(K^2\times\{t\})\}=\infty,$ for some P. EW.



Seifert manifolds
Our statement of the geometrization
theorem will make exceptions for 3-mflds
Containing essential surfaces.

But these are not the only exceptions. There are also Seifertfibered spaces.

Consider partitioning the Solid cylinder [0,1]xD into lines [0,1]x[x] and gluing via (1,P)~(0,RP/1/2T(P)). The result is a <u>Solid torus</u> Partitioned by <u>Circles</u>.

Most of these intersect the disk 203 x D<sup>2</sup> 1 times, but [0,1] × {0} is an exceptional fiber.

The twisted solid torus is another fibered torus. Its regular fibers have tength 2.

## Seifert manifolds Defin: A Seifert fibration of a 3-manifold X is a partition of X into circles - called fibers - such that, for every circle K, there exist · a subset UCX containing K; · a rational number P/q E Q; · a homeomorphism I from U to either the solid torus S'XD2 or the twisted solid torus S'XD2; S.t. (1) U is a union of fibers; solid (2) 4 sends K to the core of the image (twisted) torus; (3) I sends the partition of X to the <u>P/2-partition of</u> the solid torus or the <u>standard partition of the</u> twisted solid torus. Ex The 3-sphere can be split into two solid tori, a each with the 1/1-fibration.

The general geometrization theorem

One last bit of vocab: we call (X,d) a manifold—with boundary if it's locally homeomorphic to  $\mathbb{R}_{+}^{n} = \mathbb{R}^{n-1} \times [0,\infty)$ . The boundary DX corresponds to Rx[0] A manifold has finite topological type if it's homeomorphic to X-dx for some compact manifold-with-boundary X. Thm (Thurston, Hamilton, Perelman, etc) Let (X,d) be a Connected 3-dimensional manifold with finite topological type. Then at least one of these holds: (1) X contains an essential S, RP, Tor K; (2) X admits a Seifert fibration; (3) X admits a complete, hyperbolic metric d'

S.t. id: (X,d) -> (X,d') is a nomeomorphism.

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