#### Math 4441 August 22, 2022

**GOALS** 

- 1) Define regular, parametrized curves.
- 2) See some examples.
- 3 Define reparametrization.
- 4) Identify the goal: geometric invariants.

Nice functions We call a function  $f:\mathbb{R}^m \to \mathbb{R}^n$  a  $C^k$ <u>function</u>, for some  $k \ge 1$ , if f has Continuous derivatives of all orders up to k e.g.,  $f: \mathbb{R}^2 \to \mathbb{R}$  is C if f,  $f_X$ ,  $f_Y$ fxx, fxy, fxx, f fyy are all cts Notation:  $f \in C^k(\mathbb{R}^m, \mathbb{R}^n)$ 

# Curves as functions

A parametrized curve in  $\mathbb{R}^3$  is a  $\mathbb{C}^3$  function  $\vec{\alpha}: (a, b) \to \mathbb{R}^3$ .

We say that à is regular if \( \frac{\tau'(t) \dot 0}{\tau} \)

for all  $t \in (a,b)$ .

Notation: 
$$\overrightarrow{\alpha}(t) = \begin{pmatrix} \chi(t) \\ y(t) \\ z(t) \end{pmatrix} = \begin{pmatrix} \chi(t), y(t), z(t) \end{pmatrix}$$

$$\Rightarrow \overrightarrow{\alpha}'(t) = \frac{d\overrightarrow{\alpha}}{dt} = \begin{pmatrix} \chi'(t) \\ y'(t) \\ z'(t) \end{pmatrix} = \begin{pmatrix} \chi'(t), z'(t) \\ z'(t) \end{pmatrix}$$

### Remarks / Vocabulary

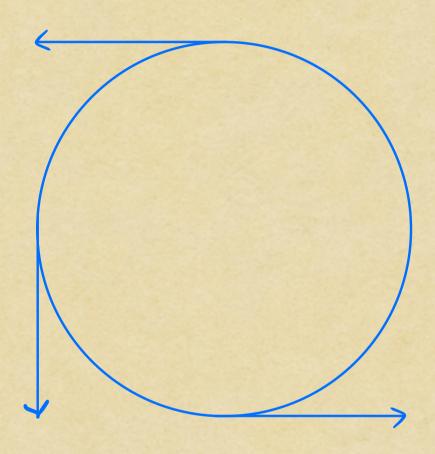
- (1) We'll often refer to the independent variable t as <u>time</u>.
- 2) The derivative d'(t) is called the <u>velocity</u> <u>vector</u> of a.

Warning: Need to choose a value of t to get a vector!

3) The speed of à is given by [à'lt].

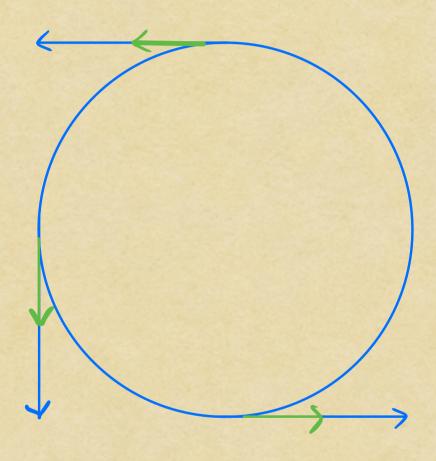
Example 1 Describe the curve  $\vec{\alpha}:(0,2\pi)\to\mathbb{R}$ defined by  $\vec{\alpha}(t) := (2\cos t, 2\sin t, 0).$ Plot à (t) at t= T/2, T, 3 T/2. Circle of radius 2 centered @ origin, in Xy-plane  $\vec{\alpha}'(t) = (-2 \sin t, 2 \cos t, 0)$  $\vec{a}'(T/2) = (-2, 0, 0)$  $\vec{a}'(\pi) = (0, -2, 0)$ 元(3元)=(2,0,0)

## Example 1, cont'd



Example 2 Describe the curve  $\beta:(0,6\pi)\longrightarrow\mathbb{R}^3$ defined by  $\beta(u) := (2\cos(\frac{u}{3}), 2\sin(\frac{u}{3}), 0)$ . Plot B'(u) at u = 3 T/2, 3 TT, 9 T/2. Circle of radius 2 centered @ origin, in Xy-plane  $\overline{\beta}(u) = \left(-\frac{2}{3}\sin\left(\frac{\pi}{3}\right), \frac{2}{3}\cos\left(\frac{\pi}{3}\right), 0\right)$  $\frac{7^{3}(3\pi)}{3^{3}} = (-\frac{2}{3}, 0, 0)$   $\frac{7^{3}(3\pi)}{3^{3}} = (0, -\frac{2}{3}, 0)$  $\overline{\beta}'(911/2) = (\frac{2}{3}, 0, 0)$ 

#### Example 2, contid



#### Didn't make it very far :

#### Curves as functions

The preceding examples illustrate an important point: while treating curves as functions is computationally helpful, we want to study the images of these functions.

We need a way to treat à and B as the same curve. Reparametrizations

A (1-dimensional) Ck reparametrization is a bijective function

g:(c,d) -> (a,b)

such that g i g are both C functions

Note: For curves we need  $k \ge 3$ We'll usually take  $k = \infty$  Example 3 Consider  $\vec{\alpha}: (0,2\pi) \longrightarrow \mathbb{R}^3$ t > (2 cost, 2 sint, 0)  $\vec{\beta}:(0,6\pi)\longrightarrow \mathbb{R}^3$  $u \longmapsto \left(2\cos\left(\frac{4}{3}\right), 2\sin\left(\frac{4}{3}\right), 0\right)$ from before. Find a reparametrization g:(c,d) -> (a,b) Such that  $\vec{\beta} = \vec{\alpha} \cdot g$ .  $g:(0,6\pi)\longrightarrow(0,2\pi)$ U 1-> 1/3  $(d \circ g)(u) = \overrightarrow{a}(g(u)) = \overrightarrow{a}(\frac{4}{3})$ a, but replace t with 1/3

By design, reparametrizing does not change the image of a curve.

Proposition. Let  $\vec{\alpha}:(a,b)\to\mathbb{R}^3$  be a regular curve,  $g:(c,d)\to(a,b)$  a reparametrization. Then  $\vec{\beta}:=\vec{\alpha}\circ g:(c,d)\to\mathbb{R}^3$  is a regular curve, and  $im(\vec{\alpha})=im(\vec{\beta})$ .

In the above circumstance, we say that  $\vec{\beta}$  is a reparametrization of  $\vec{d}$ 

(Proof.) We'll have im  $(\vec{\beta}) = im(\vec{a})$  because g is <u>Surjective</u>.

We need to check that  $\vec{\beta}$  is regular.

Let's use the variables te(a,b) {ue(c,d).

Then

$$\frac{d\vec{\beta}}{du} = \frac{d}{du}(\vec{a} \circ g) = \frac{d\vec{a}}{dt}(g(u)) \cdot \frac{dg}{du},$$

and we need de to. By assumption, de to

so it's enough to check that  $\frac{dq}{du} \neq 0$ .

For this, we can use the chain rule again.

For any ue (c,d), we have

$$(g^{-1} \circ g)(u) = \frac{u}{du} \Rightarrow \frac{1}{du}(g^{-1} \circ g) = 1$$

On the other hand,
$$1 = \frac{d}{du} \left( \frac{1}{9} \cdot 9 \right) = \frac{d9}{dt} \cdot \frac{d9}{du},$$

so  $\frac{dg}{du} \neq 0$ , as desired.

reparametrizations of chain rule





Here's a useful result that we won't prove.

Theorem. If  $\vec{\alpha}$  and  $\vec{\beta}$  are injective, regular, parametrized curves with im  $(\vec{\alpha}) = \text{im}(\vec{\beta})$ , then there is a reparametrization g such that  $\vec{\beta} = \vec{\alpha} \circ g$ .

Idea: Set  $g = \vec{Q} \circ \vec{\beta}$ .

#### Geometric invariants

Our first goal in this course is to study images of curves. The preceding results tell us that this means studying <u>Parametrized curves</u>, up to <u>reparametrization</u>.

A geometric invariant of a regular, parametrized curve à is any mathematical quantity which doesn't change when we replace à with a reparametrization à 09.